

Model: BTC-8120 Instruction Manual

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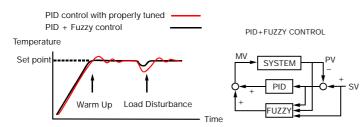
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1. INTRODUCTION

This manual contains information for the installation and operation of the Brainchild model BTC-8120 Fuzzy Logic micro-processor based

The Fuzzy Logic is an essential feature of this versatile controller. Although PID control has been widely accepted by industries, yet it is difficult for PID control to work with some sophistic systems efficiently for examples systems of second order, long time-lag, various set points, various loads, etc. Because of disadvantage of controlling principles and fixed values of PID control, it is inefficient to control the systems with plenty of varieties, and the result is obviously frustrating for some systems. The Fuzzy Logic control can overcome the disadvantage of PID control, it controls the system in a efficient way by experiences it had before. The function of Fuzzy Logic is to adjust the PID values indirectly in order to making the manipulation output value MV adjusts flexibly and quickly adapt to various processes. By this way, it enables a process to reach its predetermined set point in the shortest time with minimum overshooting during tuning or external disturbance. Different from PID control with digital information, the Fuzzy Logic is a control with language information.



In addition, this instrument has functions of single stage ramp and dwell, auto-tunung and manual mode execution. Ease of use is also an essential feature with it.

2. NUMBERING SYSTEM

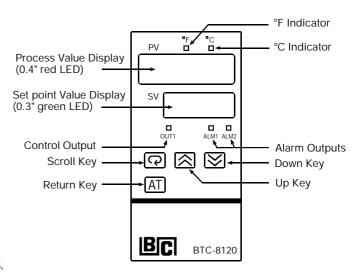
RS-485

Other

4-20mA re-transmission 0-20mA re-transmission

. NUMBI	NUMBERING SYSTEM		
Model No. — (1) (2) (3) (4) (5) (6) (7) (8)			
(1) Powe			
4	90-264VAC		
5	20-32VAC/VDC		
9	Other		
(2) Signa	al Input		
5	Configurable (Universal)		
9	Other		
(3) Rang	je Code		
1	Configurable		
9	Other		
(4) Cont	rol Mode		
3	PID / ON-OFF Control		
(5) Outp	out 1 Option		
0	None		
1	Relay rated 3A/240VAC resistive		
2	SSR Drive rated 20mA/24V		
3	4-20mA linear, max. load 500 ohms (Module OM93-1)		
4	0-20mA linear, max. load 500 ohms (Module OM93-2)		
5	0-10V linear, min. impedance 500K ohms (Module OM93-3)		
9	Other		
(6) Outp	(6) Output 2 Option		
0	None		
(7) Alarm Option			
0	None		
2	Dual relay rated 2A/240VAC resistive		
9	Other		
(8) Com	munication		
0	None		

3. FRONT PANEL DESCRIPTION



4. INPUT RANGE & ACCURACY

IN	Sensor	Input Type	Range(°C)	Accuracy
0	J	Iron-Constantan	-50 to 999 °C	±2°C
1	K	Chromel-Alumel	-50 to 1370 °C	±2°C
2	T	Copper-Constantan	-270 to 400 °C	±2°C
3	E	Chromel-Constantan	-50 to 750 °C	±2°C
4	В	Pt30%RH/Pt6%RH	300 to 1800 °C	±3°C
5	R	Pt13%RH/Pt	0 to 1750 °C	±2°C
6	S	Pt10%RH/Pt	0 to 1750 °C	±2 °C
7	N	Nicrosil-Nisil	-50 to 1300 °C	±2°C
8	RTD	PT100 ohms(DIN)	-200 to 400 °C	±0.4 °C
9	RTD	PT100 ohms(JIS)	-200 to 400 °C	±0.4 °C
10	Linear	-10mV to 60mV	-1999 to 9999	±0.05%

5. SPECIFICATIONS

INPUT

Thermocouple (T/C): type J. K. T. F. B. R. S. N.

PT100 ohm RTD (DIN 43760/BS1904 or JIS) RTD: Linear -10 to 60 mV, configurable input attenuation Range: User configurable, refer to Table above

Accuracy: Refer to Table above Cold Junction Compensation: 0.1 °C/ °C ambient typical Sensor Break Protection: Protection mode configurable External Resistance: 100 ohms max.

Normal Mode Rejection: 60 dB Common Mode Rejection: 120dB Sample Rate: 3 times / second

CONTROL

0 - 200 °C (0-360°F) **Proportion Band:** Reset (Integral): 0 - 3600 seconds Rate (Derivative): 0 - 1000 seconds

Ramp Rate: 0 - 200.0 °C /minute (0 - 360.0 °F /minute)

Dwell: 0 - 3600 minutes

ON-OFF: With adjustable hysteresis (0-20% of SPAN)

Cycle Time: 0-120 seconds

Control Action: Direct (for cooling) and reverse (for heating)

POWER

Rating: 90-264VAC, 50/60Hz Consumption: Less than 5VA

ENVIRONMENTAL & PHYSICAL

Operating Temperature: -10 to 50 °C

Humidity: 0 to 90 % RH (non-codensing) 20M ohms min. (500 VDC) Insulation: Breakdown: AC 2000V, 50/60 Hz, 1 minute 10 - 55 Hz, amplitude 1 mm Vibration:

 $200 \text{ m/ s}^2 (20g)$ Shock: 240 grams Net Weight:

Housing Materials: Poly-Carbonate Plastic Safety: Complied UL, CSA

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6. INSTALLATION

6.1 DIMENSIONS & PANEL CUTOUT

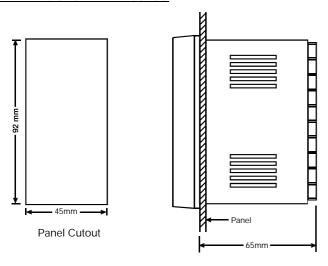
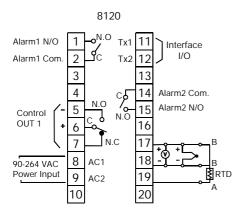


Figure 6.1 Mounting Dimensions

6.2 WIRING DIAGRAM



7. CALIBRATION

Note: Do not proceed through this section unless their is a genuine need to re-calibrate the controller. All previous calibration data will be lost. Do not attempt re-calibration unless you have available appropriate calibration equipment. If calibration data is lost, you will need to return the controller to you supplier who may apply a charge for re-calibration.

Prior to calibration ensure that all parameter settings are correct (input type, $^{\circ}$ C / $^{\circ}$ F, resolution, low range, high range).

- Remove sensor input wiring and connect a standard input simulator of the correct type to the controller input. Verify correct polarity. Set simulated signal to coincide with low process signal (e.g. zero degrees).
- 2. Use the Scroll Key until the " L L AL " appears on the PV Display. (Refer to 8.2)
- Use the Up and Down Keys until the SV Display represents the simulated input.
- Press the Return Key for at least 6 seconds(maximum 16 seconds), then release. This enters the low calibration figure into the controller's non-volatile memory.
- 5. Press and release the Scroll Key. " HLBL " appears on the PV Display. This indicates the high calibration point.
- Increase the simulated input signal to coincide with high process signal (e.g. 100 degrees).
- Use the Up and Down Keys until the SV Display represents the simulated high input.
- Press the Return Key for at least 6 seconds (maximum 16 seconds), then release. This enters the high calibration figure into the controller's non-volatile memory.
- Turn power off the unit, remove all test wiring and replace sensor wiring (observing polarity).

8. OPERATION

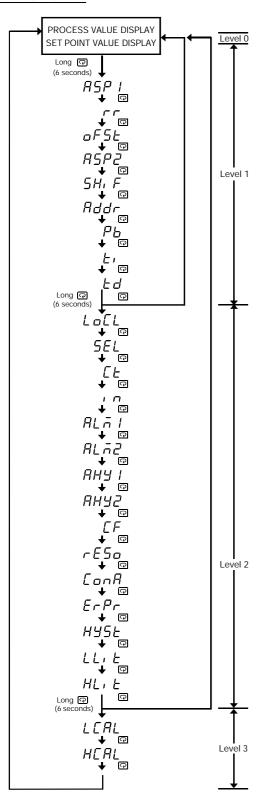
8.1 KEYPAD OPERATION

* With power on, it has to wait for 12 seconds to memorize the new values of parameters once it been changed.

TOUCHKEYS	FUNCTION	DESCRIPTION
Q	Scroll Key	Advance the index display to the desired position. Index advanced continuously and cyclically by pressing this keypad.
	Up Key	Increases the parameter
₩	Down Key	Decreases the parameter
AT	Return Key	Resets the controller to its normal status. Also stops auto-tuning, output percentage monitoring and manual mode operation.
Press Q for 6 seconds	Long Scroll	Allows more parameters to be inspected or changed.
Press AT for 6 seconds	Long Return	Executes auto-tuning function Calibrates control when in calibration level
Press Q and AT	Output Percentage Monitor	Allows the set point display to indicate the control output value.
Press and AT for 6 seconds	Manual Mode Execution	Allows the controller to enter the manual mode.

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8.3 PARAMETER DESCRIPTION



The "return" key can be pressed at any time. This will prompt the display to return to the Process value/Set point value. Power Applied:

- 1. B I = D Displayed for 4 seconds. (Software Version 3.6 or higher)
- 2. **8.8.8.8. 8.8.8.8.** LED test.

All LED segments must be lit for 4 seconds.

3. Process value and set point indicated.

INDEX CODE	DESCRIPTION ADJUSTMENT RANGE	**DEFAUL SETTING	
SV	Set point Value Control *Low Limit to High Limit Value	Undefined	
85P I 85P 2	Alarm Set point Value * Low Limit to High Limit Value.(if \$\begin{align*} \beta \in \begin{align*} \beta \lambda \in \beta \lambda \in \beta \lambda \in \begin{align*} \beta \lambda \in \beta	200°C	
rr	Ramp Rate for the process value to limit an abrupt change of process (Soft Start) * 0 to 200.0 °C (360.0 °F) / minute (if , n = 0 to 9) * 0 to 3600 unit / minute (if , n = 10)	0 °C / min.	
oF5Ł	Offset Value for Manual Reset (if $E_{\nu} = 0$) * 0 to 100%	0.0 %	
SH: F	Offset shift for process value * -111 °C to 111 °C	0 ℃	
Addr	Address Code for Digital Transmission * 0-31: For Digital Transmission	0	
РЬ	Proportional Band * 0 to 200 °C (set to 0 for on-off control)	10 °C	
Ŀ،	Integral (Reset) Time * 0 to 3600 seconds	120 sec.	
Еd	Derivative (Rate) Time * 0 to 1000 seconds	30 sec.	
LoCL	Local Mode 0: No control parameters can be changed 1: Control parameters can be changed	1	
SEL	Parameter Selection (allows selection of additional parameters to be accessible at level 0 security) 0: None 6:	0	
۲٤	Proportional Cycle Time * 0 to 120 seconds	Relay Pulsed Voltage Linear Volt/mA	20 1 0
ı n	Input Mode Selection 0: J type T/C 6: S type T/C 1: K type T/C 7: N type T/C 2: T type T/C 8: PT100 DIN 3: E type T/C 9: PT100 JIS 4: B type T/C 10: Linear Voltage or Current 5: R type T/C (Note: T/C-Close solder gap J3, RTD- Open J3)	T/C RTD Linear	0 8 10
AL⊼ I AL⊼2	Alarm Mode Selection 0: Process High Alarm 1: Process Low Alarm 2: Deviation Low Alarm 4: Inhibit Process High Alarm 4: Inhibit Process High Alarm 5: Inhibit Process Low Alarm 6: Inhibit Deviation High Alarm 7: Inhibit Deviation Low Alarm (12 & 13 only available with alarm 1)	0	
AHY I	Hysteresis of Alarm 1 * 0 to 20% of SPAN	0.5%	
E F	°C / °F Selection 0: °F, 1: °C	1	
r E S o	Resolution Selection 0: No Decimal Point 1: 1 Digit Decimal 3: 3 Digit Decimal	0	
ConA	(2 & 3 may only be used for linear voltage or current ' n = 10) Control Action 0: Direct (Cooling) Action 1: Reverse (Heat) Action	1	
ErPr	Error Protection Output1 Alarm1 Alarm2 Output1 Alarm1 Alarm2 Output1 Alarm1 Alarm2	1	
H95E	Hysteresis for ON/OFF Control *0 to 20 % of SPAN	0.5%	
LL,E	Low Limit of Range	-50 °C	
HL, E	High Limit of Range	1000 °C	
LEAL	Low Calibration Figure	0 ℃	
	<u></u>	1	

NOTES: * Adjusting Range of the Parameter

** Factory settings. Process alarms are at fixed temperature points. Deviation alarms move with the set points value.

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8.4 AUTOMATIC TUNING

- 1. Ensure that controller is correctly configured and installed.
- 2. Ensure Proportional Band 'Pb' is not set at '0'.
- Press Return Key for at least 6 seconds (maximum 16 seconds). This initialises the Auto-tune function. (To abort auto-tuning procedure press Return Key and release).
- 4. The Decimal point in lower right hand corner of PV display flashes to indicate Auto-tune is in progress. Auto-tune is complete when the flashing stops.
- Depending on the particular process, automatic tuning may take up to two hours. Processes with long time lags will take the longest to tune. Remember, while the display point flashes the controller is auto-tuning.

NOTE: If an AT error($\mathcal{A} \mathcal{E} \mathcal{E} \mathcal{F}$) occurs, the automatic tuning process is aborted due to the system operating in ON-OFF control(PB=0). The process will also be aborted if the set point is set to close to the process temperature or if there is insufficient capacity in the system to reach set point (e.g. inadequate heating power available). Upon completion of Auto-tune the new P.I.D. settings are automatically entered into the controller's non-volatile memory.

8.5 MANUAL P.I.D. ADJUSTMENT

Whilst the auto-tuning function selects control settings which should prove satisfactory for the majority of processes, you may find it necessary to make adjustments to these arbitrary settings from time to time. This may be the case if some changes are made to the process or if you wish to 'fine-tune' the control settings.

It is important that prior to making changes to the control settings that you record the current settings for future reference. Make slight changes to only one setting at a time and observe the results on the process. Because each of the settings interact with each other, it is easy to become confused with the results if you are not familiar with process control procedures.

TUNING GUIDE

Proportional Band

Symptom	Solution
Slow Response	Decrease PB Value
High Overshoot or Oscillations	Increase PB Value

Integral Time (Reset)

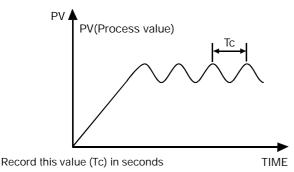
	Symptom	Solution
Slow Response		Decrease Integral Time
	Instability or Oscillations	Increase Integral Time

Derivative Time (Rate)

Symptom	Solution
Slow Response or Oscillations	Decrease Deriv. Time
High Overshoot	Increase Deriv. Time

8.6 MANUAL TUNING PROCEDURE

- Step 1: Adjust the integral and derivative values to 0. This inhibits the rate and reset action
- Step 2: Set an arbitrary value of proportional band and monitor the control results
- Step 3: If the original setting introduces a large process oscillation, then gradually increase the proportional band until steady cycling occurs. Record this proportional band value(Pc).
- Step 4: Measure the period of steady cycling



Step 5: The Control Settings are determined as follows:

Proportion Band(PB)=1.7 Pc Integral Time (TI)=0.5 Tc Derivative Time(TD)=0.125 Tc

8.7 RAMP & DWELL

The BTC-8120 controller can be configured to act as either a fixed set point controller or as a single ramp controller on power up. This function enables the user to set a pre-determined ramp rate to allow the process to gradually reach set point temperature, thus producing a 'Soft Start' function.

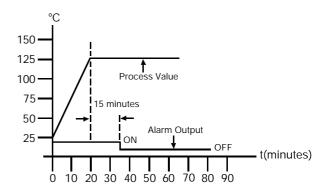
A dwell timer is incorporated within the BTC-8120 and the alarm relay can be configured to provide either a dwell function to be used in conjunction with the ramp function.

The ramp rate is determined by the ' $\Gamma\Gamma$ ' parameter which can be adjusted in the range 0 to 200.0 °C/minute. The ramp rate function is disabled when the ' $\Gamma\Gamma$ ' parameter is set to '0'.

The soak function is enabled by configuring the alarm output to act as a dwell timer. The parameter \mathcal{RLn} in needs to be set to the value 12. The alarm contact will now operate as a timer contact, with the contact being closed at power up and opening after the elapsed time set at parameter \mathcal{RSP} i.

If the controller power supply or output is wired through the alarm contact, the controller will operate as a guaranteed soak controller.

In the example below the Ramp Rate is set to 5 °C/minute, $RL\bar{n}$ I=12 and R5PI=15 (minutes). Power is applied at zero time and the process climbs at 5 °C/minute to the set point of 125 °C. Upon reaching set point, the dwell timer is activated and after the soak time of 15 minutes, the alarm contact will open, switching off the output. The process temperature will eventually fall at an undetermined rate.



The dwell function may be used to operate an external device such as a siren to alert when a soak time has been reached.

 $RL\bar{n}$ / need to be set to the value 13. The alarm contact will now operate as a timer contact, with the contact being open on the initial start up. The timer begins to count down once the set point temperature is reached. After the setting at RSP / has elapsed, the alarm contact

9. ERROR MESSAGES

	†	
Symptom	Cause (s)	Solution (s)
SbEr	Sensor break error	Replace RTD or sensor Use manual mode operation
LLEr	Process display beyond the low range set point	Re-adjust <u>L</u> <u>L</u> , <u>L</u> value
HLEr	Process display beyond the high range set point	Re-adjust HL, E value
AHEr	Analog hybrid module damage	Replace module. Check for outside source of damage such as transient voltage spikes
ALEr	Incorrect operation of auto tune procedure Prop. Band set to 0	Repeat procedure. Increase Prop. Band to a number larger than 0
oPEr	Manual mode is not allowable for an ON-OFF control system	Increase proportional band
[SE-	Check sum error, values in memory may have changed accidentally	Check and reconfigure the control parameters